

Newsletter 49, May 1997

TC10 news #49

Contents:
=====

Update: GREC'97 - Int. Workshop on Graphics Recognition
Update: CVPR'97 - Advance Program and Hotel Info.
Update: ICCV'98 - Deadline Extended
Update: BSDIA97 - New Dates
Update: Integrating Photogrammetric Techniques with Scene Analysis

CFP: ISMM'98 (Amsterdam) - Int. Symp. on Mathematical Morphology
CFP: Special Issue on Learning in Autonomous Robots
CFP: IEEE Expert Special Issue on Autonomous Vehicles

Software: Compilation of existing vision software libraries

Announcement: IEEE Workshp on Generic Object Recognition (Puerto Rico)
Announcement: TC-2 Newsletter

Dear TC10 members and friends,

Welcome to TC10 news #49. The most important announcement in this newsletter is the update on GREC'97 workshop. Since GREC is the primary workshop of this TC, I hope most of you will be able to participate in the workshop.

I have recently received several e-mail inquiries about the Graphics Recognition Contest to be held at GREC'97. People have aksed when the sample images, etc., will be available for download. I will make the images and groundtruth data available within a week. You should be able to download the images and data through the contest web page --

<http://www.iapr-tc10.or.kr/contest.htm> If you cannot find the images there on or after April 27, please send me e-mail and I will look into the problem. In the next few days, I will send out a detailed update on the contest to the TC10 list.

-Atul

> From: Karl Tombre <Karl.Tombre@loria.fr>
> Subject: Update: GREC'97 - Int. Workshop on Graphics Recognition

GREC'97 Update

Web page: <http://www.loria.fr/~tombre/grec97.html>

Following the success of the First International Workshop on Graphics Recognition (Penn State University, University Park, Pennsylvania, August 9-11, 1995), the second edition in this series, GREC'97, will be held on August 22-23, 1997, in Nancy, France.

We received 51 submissions, and 41 were selected for presentation.

The workshop will be held just after ICDAR'97, the 4th International Conference on Document Analysis and Recognition (Ulm, Germany, August 18-20, 1997). Nancy is only a 4 hours drive from Ulm and the two cities are directly connected by train. Hopefully, this August week will be packed with interesting scientific discussions, but also with more informal social contacts, for scientists interested in document analysis, and more specifically in graphics recognition.

The workshop will be held in the LORIA building shared by INRIA Lorraine and CRIN/CNRS. We have decided to limit attendance to around 75 persons, in order to ensure active participation by all attendees. The program has also been built to maximize scientific exchanges and to ensure a true working group atmosphere.

Six topical sessions are planned. Each of them will start with an introduction to the state of the art of the adressed topic by a leading scientist. This will be followed by short, to-the-point presentations of technical contributions; the aim is not to deliver a formal talk, but rather to describe the details of the author's contribution to the field. To provide enough time for exchanges, each session will close with a 25-minute panel discussion, with participation both by the authors in the session and by the audience. Each panel discussion will be summarized in a report written by the session moderator after the workshop, and published in the post-workshop book.

Pre-proceedings of all contributed papers will be available at the workshop for the participants. After the workshop, the program committee will select key papers, including reports from the panel discussions and possibly invited papers, and publish them in revised form as a book in the "Lecture Notes in Computer Science" series.

A graphics recognition contest will be held at the workshop. The contest will test the participants' ability to segment text from

graphics and to recognize graphical primitives such as lines, arcs, and circles, both solid and dashed. The specifications and the evaluation protocol for the contest will be intentionally kept simple in order to encourage participation. Like the dashed line detection contest of GREC'95, it will be possible for potential participants to generate synthetic images of increasing complexity in order to test and refine their algorithms. For more details on this contest, including sample raster images (both synthetic and real) along with ground truth data, please visit the contest's web site at <http://graphics/iapr-tc10/contest.html>.

Breaks for informal discussions, French cuisine lunch buffets, and a number of social events are also planned during and after the workshop.

Preliminary program
=====

Thursday 21-08-1997

20:00-22:00 Welcome reception

Friday 22-08-1997

08:30-09:30 Welcome and registration
09:30-10:00 General introduction
10:00-10:30 Break
10:30-12:15 Vectorization and separation
12:15-14:00 Lunch
14:00-15:55 Engineering drawings
15:55-16:25 Break
16:25-18:00 Business Graphics and Forms
20:00-24:00 Banquet and canal cruise

Saturday 23-08-1997

08:00-09:00 Contest preparation
09:00-10:00 Maps
10:00-10:30 Break
10:30-11:40 Maps (continued)
11:40-12:40 Contest
12:40-14:00 Lunch
14:00-15:45 Diagrams and Symbol Recognition
15:45-16:15 Break
16:15-17:30 Performance Evaluation
17:30-18:00 Concluding remarks
20:00-23:00 Optional sightseeing tour of Nancy

Sunday 24-08-1997

09:00-18:00 Optional tour to the Vosges mountains

Registration
=====

The registration fees for the workshop are as following:

- Before June 30: 1200 FRF
- After June 30: 1500 FRF

The registration fee for the workshop includes the proceedings, the welcome reception, the lunch buffets, the workshop banquet, and the breaks.

Accompanying persons pay 300 FRF for the banquet, 150 FRF for the welcome reception, and 150 FRF for each buffet lunch.

More Information
=====

Up to date information about the workshop can be found at the following WWW URL: <http://www.loria.fr/~tombre/grec97.html>

If you wish to take part in this workshop, but haven't submitted a paper to it, please contact the organizers by email to grec97@loria.fr, so that we can send registration information to you.

We look forward to welcoming you in Nancy for an exciting workshop.

The organizers

> From: majordom@bigpine.csee.usf.edu
> Subject: Update: CVPR'97 - Advance Program and Hotel Info.

The CVPR '97 web page <http://marathon.csee.usf.edu/cvpr97.html> now has been updated with

a draft version of the advance program

information for making hotel reservations

On-line registration for the conference and associated workshops
can be accessed from the page as well.

> From: majordomo admin <majordomo@bigpine.csee.usf.edu>
> Subject: Update: ICCV'98 - Deadline Extended

The deadline for submitting papers to the 1998
International Conference on Computer Vision has
been extended to 30 April.

The chairs of ICCV '98 emphasize that this is the
very last extension.

The latest information on ICCV and affiliated
workshops is posted at

<http://www.umiacs.umd.edu/users/lrd/iccv/index.html>
or
<http://www.cse.iitb.ernet.in/~iccv98>

I have abbreviated this CFP. The full length first CFP for this
conference appeared in TC10 news #46 which is available at the TC10
web site. You can also get the full version from the conference web
site.

-Atul

> From: "Nabeel A. Murshed" <murshed@rla01.pucpr.br>
> Subject: Update: BSDIA97 - New Dates

First Brazilian Symposium on Document Image Analysis
November 03-05, 1997, Curitiba - Brazil

Second Call for Papers

You are invited to participate in the First Brazilian Symposium on
Document Image Analysis that will be held in Curitiba - Brazil on
November 03 - 05, 1997. The symposium aims at promoting and motivating
researches and developments in the fields of Handwriting and Graphics
Recognition, Storage and Information Retrieval, Workflow and Document
System Architectures; and providing a forum for researchers, students,
developers and end-users, from academia and industry, to discuss and
exchange topics related to those areas. The symposium is organized by
the Lab. of Document Image Analysis and Neural Networks (LADIANN) of the
Pontifical Catholic University of Paran?(PUC-PR).

>>>>>>>> New Dates <<<<<<<<<<<

Important Dates

Paper submission:

To be received by April 30, 1997

Notification of acceptance:

To be mailed out on June 30, 1997

Camera-ready submission:

To be received by July 30, 1997

Further Information

For further information on BSDIA?7,
please contact the program chair:

BSDIA?7

Prof. Nabeel A. Murshed

Lab. of Document Image Analysis and Neural Networks (LADIANN)

Programa de Mestrado em Inform?ica Aplicada, PUC-PR

R. Imaculada Concei?ao, 1155

Curitiba, PR 80215-901 - Brasil

email: murshed@rla01.pucpr.br,

Fax: +55(41) 330 - 1620, Tel.: +55(41) 330 - 1668

Conference Home page: <http://epsilon.pucpr.br/bsdia97>

> From: Chris McGlone <Chris_McGlone@maps.cs.cmu.edu>
> Subject: Update: Integrating Photogrammetric Techniques with Scene Analysis

Integrating Photogrammetric Techniques with
Scene Analysis and Machine Vision III

Part of AeroSense '97

SPIE's 11th Annual International Symposium on

Aerospace/Defense Sensing, Simulation, and Controls

Marriott Orlando World Center Resort and Convention Center
Orlando, Florida, USA

Monday-Wednesday 21-23 April 1997

SPIE Proceedings Vol. 3072

http://www.spie.org/web/meetings/calls/or97/or97_home.html

Conference Chairs:

David M. McKeown, Jr., Carnegie Mellon Univ.;

J. Chris McGlone, Carnegie Mellon Univ.;

Olivier Jamet, Institut Géographique National (France)

Program Committee:

Ian J. Dowman, Univ. College London (UK);
Christian Heipke, Technische Univ. Muenchen (FRG);
Edward M. Mikhail, Purdue Univ.;
Walter J. Mueller, GDE Systems, Inc.

Session topics include:

- * Photogrammetric Systems (6 papers)
- * Sensor Systems (4 papers)
- * Road Detection and Extraction, (3 papers)
- * DEM/DTM Matching and DEM Representation, (7 papers)
- * Building Modeling and Extraction (5 papers)
- * Automated Registration (6 papers)

Each presentation will be allowed 30 minutes with
5 minutes reserved for questions and discussion.

The full program is available at

<http://www.cs.cmu.edu/~MAPSLab/spie-prog.html>

or

http://www.spie.org/web/meetings/programs/or97/conferences/or97_3072.html

In conjunction with this conference, a joint inaugural meeting for
International Society for Photogrammetry and Remote Sensing
Working Groups II/6 and II/8 will be held on Monday, 21 April.
Please see the accompanying announcement for details.

REGISTRATION AND HOTEL INFORMATION

Registration can be accomplished interactively on the conference web site:

http://www.spie.org/info/or97_regform.html

or you can receive an ascii form by sending a message to

info-spie-request@spie.org

with the BODY of the message (NOT the subject line)

send or97_regform

Alternatively, phone or fax SPIE to get a registration form.

1-360-676-3290

1-360-647-1445 (fax)

The pre-registration cutoff date for reduced rates is April 4.

Online hotel registration information is available on the conference web page:

http://www.spie.org/web/meetings/calls/or97/or97_general.html

> From: Henk Heijmans <Henk.Heijmans@cwil.nl>
> Subject: CFP: ISMM'98 (Amsterdam) - Int. Symp. on Mathematical Morphology

ISMM '98

Preliminary Call for Papers

INTERNATIONAL SYMPOSIUM ON MATHEMATICAL MORPHOLOGY

and its Applications to Image and Signal Processing IV

June 3-5, 1998, Amsterdam, The Netherlands

This symposium is the fourth in a series of international workshops
devoted to the area of mathematical morphology and its applications in
image and signal processing. The scientific programme includes
presentation of invited talks and contributed papers. The size of the
workshop will be limited in order to enable interaction between the
participants.

SUBMISSION PROCEDURES:

Prospective authors are invited to submit five copies of a full paper
devoted to any topic in the area of mathematical morphology to the
address listed below. The manuscript should include a separate title
page, containing the names and the addresses of the authors (including
e-mail and fax), an abstract of up to 200 words, and 3-5 keywords.
Papers submitted by fax or email will not be considered.

Acceptance of papers is based on appropriateness of the topic and on
quality, novelty, and clarity of exposition. Each paper will be
reviewed by at least two members of the Programme Committee using a
blind procedure, and their reviews will be returned to the author.

Accepted papers will appear in the proceedings volume published by
Kluwer in their Computational Imaging and Vision series. This volume
will be available at the beginning of the workshop. The final paper has
to be prepared using the LaTeX typesetting system using the style
file provided by the organisers (see web-site below), and should be
limited to 8 pages including artwork and references.

IMPORTANT DATES:

September 30, 1997: Submission of full paper

December 15, 1997: Notification of acceptance
February 15, 1998: Camera-ready full paper

SUBSIDIARY GRANTS:

The organisers plan to make available a very limited number of subsidiary grants for participants from countries in Eastern Europe and former Soviet Union. These grants will cover traveling expenses (cheapest option), full registration and hotel expenses. The main criterion for achieving a grant is that the applicant is the (first) author of an accepted paper. Selection will be on the base of paper quality. Applications for these grants have to be submitted to the ISMM'98 secretariat.

INFORMATION:

For further information please contact the ISMM'98 secretariat:

Mrs. L.M. v.d. Eersten-Schultze email: lieke@cw.nl
CWI tel: +31 20 592 4189
Kruislaan 413 fax: +31 20 592 4199
NL 1098 SJ Amsterdam
The Netherlands

Further information about the workshop (conference site, registration, hotels, invited speakers, LaTeX style file) will become available at the following internet site:
<http://www.cwi.nl/projects/morphology/ismm98/>

CONFERENCE CHAIRS:

Henk J.A.M. Heijmans Jos B.T.M. Roerdink
CWI Department of Computing
Science
Kruislaan 413 University of Groningen
NL 1098 SJ Amsterdam P.O. Box 800
The Netherlands 9700 AV Groningen
The Netherlands

email: henkh@cw.nl roe@cs.rug.nl
tel: +31 20 5924057 +31 50 3633931
fax: +31 20 5924199 +31 50 3633800

PROGRAMME COMMITTEE:

Banon, G.J.F. Brazil
Boomgaard, R. van den The Netherlands
Dougherty, E.R. USA
Goutsias, J. USA
Kunt, M. Switzerland
Maragos, P. Greece
Marshall, S. UK
Meyer, F. France
Ronse, C. France
Salembier, Ph. Spain
Schafer, R.W. USA
Schmitt, M. France
Schonfeld, D. USA
Serra, J. France
Vincent, L. USA
Wojciechowski, K. Poland

LOCAL ARRANGEMENTS:

Eersten-Schultze, L.M. v.d.
Snijders, F.A.M.

> From: hexmoor@cs.Buffalo.EDU
> Subject: CFP: Special Issue on Learning in Autonomous Robots

<http://www.cs.buffalo.edu/~hexmoor/autonomous-robots.html>

Call for papers
Autonomous Robots Journal
Special Issue on Learning in Autonomous Robots

Guest editors: Henry Hexmoor and Maja Mataric

Submission Deadline: August 15, 1997

Autonomous Robots is an international journal published by Kluwer Academic Publishers, Editor-in-Chief: George Bekey

Current applications of machine learning in robotics explore learning behaviors such as obstacle avoidance, navigation, gaze control, pick and place operations, manipulating everyday objects, walking, foraging, herding, and delivering objects. It is hoped that these are first steps toward robots that will learn to perform complex operations ranging from folding clothes, cleaning up toxic waste and oil spills, picking up after the children, de-mining, look after a summer house, imitating a human teacher, or overseeing a factory or a space mission.

As builders of autonomous embedded agents, researchers in robot

learning deal with learning schemes in the context of physical embodiment. Strides are being made to design programs that change their initial encoding of know-how to include new concepts as well as improvements in the associations of sensing to acting. Driven by concerns about the quality and quantity of training data and real-time issues such as sparse and low-quality feedback from the environment, robot learning is undergoing a search for quantification and evaluation mechanisms, as well as for methods for scaling up the complexity of learning tasks.

This special issue of Autonomous Robots will focus on novel robot learning applications and quantification of learning in autonomous robots. We are soliciting papers describing finished work preferably involving real manipulator or mobile robots. We invite submissions from all areas in AI and Machine Learning, Mobile Robotics, Machine Vision, Dexterous Manipulation, and Artificial Life that address robot learning.

Submitted papers should be delivered by June 1, 1997. Authors intending to submit a manuscript should contact Henry Hexmoor as soon as possible to discuss paper ideas and suitability for this issue.

Manuscripts should be typed or laser-printed in English (with American spelling preferred) and double-spaced. Both paper and electronic submission are possible, as described below.

For paper submissions, send five (5) copies of submitted papers (hard-copy only) to:

Dr. Henry Hexmoor
Department of Computer Science
State University of New York at Buffalo
226 Bell Hall
Buffalo, NY 14260-2000
U.S.A.
PHONE: 716-645-3197
FAX: 716-645-3464

For electronic submissions, use Postscript format, ftp the file to <ftp.cs.buffalo.edu>, and send an email notification to hexmoor@cs.buffalo.edu

Detailed ftp instructions:

```
compress your-paper (both Unix compress and gzip commands are ok)
ftp ftp.cs.buffalo.edu (but check in case it has changed)
give anonymous as your login name
give your e-mail address as password
set transmission to binary (just type the command BINARY)
cd to users/hexmoor/
put your-paper
```

send me an email notification hexmoor@cs.buffalo.edu to let me know you transferred the paper

Relevant Dates:

August 15, 1997 submission deadline

November 15, 1997 review deadline

December 1, 1997 acceptance/rejection notifications to the authors

> From: Alberto Broggi <broggi@CE.UniPR.IT>
> Subject: CFP: IEEE Expert Special Issue on Autonomous Vehicles

C A L L F O R A R T I C L E S

IEEE Expert Magazine

VISION-BASED DRIVING ASSISTANCE IN VEHICLES OF THE FUTURE
<http://www.ce.unipr.it/expert>

ALBERTO BROGGI, Guest Editor

Thanks to the increasing computational power of current computer systems and to the reduced costs of image-acquisition devices, in the last few years vision-based sensing of the surrounding environment has gained a strategic importance not only in military applications, but also in the automotive field. This special issue will address the problems of autonomous vehicle driving, describe common techniques, and present the state of the art. Suggested topics include

- Vision-based guidance of unmanned vehicles.
- Analysis of real-time constraints for vehicle driving.
- Vehicle navigation in unknown environments.
- Integration of specialized hardware on vehicles.
- Description of research prototypes.
- Legal aspects.
- Analysis of future trends.

Expert seeks two kinds of articles:

- TUTORIALS and SURVEYS introducing this field and reviewing the state of the art or the state of the practice of work done in this area, with the aim of comparing different solutions and techniques. Such

articles should be approximately 6,000 words (9-10 magazine pages), with extensive references to widely available published works. One or two such articles will likely be included.

- ARTICLES describing prototypes of autonomous vehicles developed worldwide by universities, research centers, corporations, and government institutions. These articles should describe both the techniques and the results obtained, and the references should allow the interested reader to follow up on both. Articles describing the fusion of data coming from sensors other than vision are also welcome. These articles should be from 5,500 to 6,000 words (8-9 magazine pages), with no more than 12 references. A consistent and useful set of definitions and examples can often help explain the underlying mathematics. Such aids can be presented as sidebars in the published article. Four or five such articles will likely be included.

All authors should submit six hard copies of their article by December 20, 1997, to the guest editor, Alberto Broggi. Authors intending to submit tutorials or survey articles are encouraged to discuss this with the guest editor or to send an extended abstract to him by October 1, 1997.

Guest Editor: Alberto BROGGI
Dipartimento di Ingegneria dell'Informazione
Universita' di Parma
I-43100 Parma
ITALY
Fax 39 (521) 90-5723
a.broggi@computer.org

Schedule:
Submission of manuscripts: December 20, 1997
Acceptance/rejection notification: April 12, 1998
Revised manuscripts due: June 7, 1998
Publication: September 1998

For more information, access <http://www.ce.unipr.it/expert>

IEEE Expert: Intelligent Systems and Their Applications publishes technically substantive articles that are referenced extensively in the literature and read by 8,000-9,000 people worldwide. Expert is a magazine of applied AI - a bridge between the research community and the user community. Its readers want to learn about the tools, techniques, concepts, and systems that have potential for real-world applications. Conceptual or theoretical papers are welcome, provided they clarify and present items of importance to applications. Clear, not overly formal, writing is essential.

All articles will be carefully peer reviewed. Authors whose articles are accepted on technical grounds will work with the magazine's staff editors to arrive at a final article that is clear, straightforward, and valuable to the user community.

Full publication guidelines are available at
<http://computer.org/pubs/expert/edguide.htm>, or from the managing editor at dprice@computer.org.

I am including this message from the Vision List in case some of you don't subscribe to that. I have abbreviated the message to only include the URL's. For the full text of the message, you may access it through the Vision List, the newsgroup comp.ai.vision, or you may download this from the vision list archive.
-Atul

> From: smo@ssc.se
> Subject: Software: Compilation of existing vision software libraries

Dear vision group,

I while back I posed a question on existing vision software libraries, I have received a number of helpful replies from several people, and their replies are enclosed here. I've also taken the liberty to compile a list of URL's from their replies, and a reference, while leaving their comments in full below. I've refrained from categorizing them, since I don't have any experience in using them myself. I plan to look at several of them, given time (life is too short...).

[text deleted]

Thanks again for supplying information on software libraries!

Best regards,

S=F6ren Molander, Ph.D.	Tel. +46 (0)980 121-40
SSC Satellitbild	Fax. +46 (0)980 160-44
Product Development Dept.	Email. smo@ssc.se
P.O. Box 816	
S-981 28 Kiruna	
Sweden	
URL: <http://www.ssc.se/sb>	
<http://www.kiruna.se/~molander>	

FREE LIBRARIES

URL: <http://www.eso.org/~ndevilla/adonis/eclipse>
source: Nicholas Devillard, nDevil@eso.org

URL: <http://www.cs.cmu.edu/~cii/v-source.html>
Image Understanding Environment
URL: <http://www.aai.com/AAI/IUE/IUE.html>
Khoros
URL: <http://www.khoros.unm.edu/>
source: Karl Tombre Email: Karl.Tombre@loria.fr

URL: <http://www.robots.ox.ac.uk/~pm/horatio/index.html>
source: Anton van den Hengel hengel@cs.adelaide.edu.au
<http://www.cs.adelaide.edu.au/~hengel>

<http://www.cs.curtin.edu.au/~cdillon/ftp.html>.
source: Brendan McCane, mccane@cs.otago.ac.nz

Candela. GNU licensed package for computer vision from the CVAP group (under J-O Eklundh) in Stockholm.
URL: <http://www.nada.kth.se/cvap/software.html>
source: s=F6ren molander, smo@ssc.se

COMMERCIAL LIBRARIES/COMPANIES

URL: <http://www.catenary.com>
URL: <http://www.accusoft.com>
URL: <http://www.leadtools.com>
URL: <http://www.imagelib.com>
URL: <http://www.snowbnd.com>
URL: <http://www.pixelsoft.com>
Applied Imaging
URL: <http://www.aai.com/products.html>
HIPS package
URL: <http://www.cns.nyu.edu/home/msl/Sl.cgi>
source: Ken Thornton, ken@lnk.com, <http://www.lnk.com>

URL: <http://www.cns.nyu.edu/home/msl/hipsdescr.cgi>
source: Michael Landy, landy@nyu.edu

For remote sensing:
URL: <http://www.erdas.com>
IDL (interactive data language)
URL: <http://www.rsinc.com>
AVS system for visual programming and program interfacing:
URL: <http://www.avs.com>
source: s=F6ren molander, smo@ssc.se, <http://www.ssc.se>, =
<http://www.kiruna.se/~molander>

> From: Sven Dickinson <sven@ruccs.rutgers.edu>
> Subject: Announcement: IEEE Workshop on Generic Object Recognition (Puerto Rico)

IEEE Workshop on Generic Object Recognition

June 16, 1997 (just before '97) -- El San Juan Hotel, Puerto Rico

OBJECTIVES

In contrast to object recognition strategies which assume knowledge of the exact shape or appearance of an object, generic object recognition endeavors to recognize objects based on their coarse, prototypical shape. Although a popular topic in the 1970's, generic object recognition has given up the recognition spotlight to such schemes as alignment, geometric hashing (and other geometric invariant-based indexing), and eigenspace methods. Recently, however, interest in recognition domains where exact object geometry is unknown, e.g., content-based image retrieval and non-rigid object recognition, has revived an interest in generic object recognition. This workshop is a response to that interest.

The workshop will consist of 10-12 invited talks by prominent researchers working on generic object modeling and recognition. The talks will be approximately 25 minutes in duration with an additional panel session in the morning and one in the afternoon. A full schedule for the workshop will be added to the workshop website (<http://marathon.csee.usf.edu/recognition.html>) by the end of May, 1997.

Any further questions should be addressed to one of the co-chairs.

CO-CHAIRS

Sven J. Dickinson Ram Nevatia
Department of Computer Science and Department of Computer Science
Center for Cognitive Science University of Southern California
Rutgers University nevatia@iris.usc.edu
sven@cs.rutgers.edu

INVITED SPEAKERS

Ronen Basri, Weizmann Institute

Tom Binford, Stanford University
Kevin Bowyer, University of South Florida
Sven Dickinson, Rutgers University
Chitra Dorai, IBM Watson Research Center
David Forsyth, University of California, Berkeley
Gerard Medioni, University of Southern California
Jean Ponce, University of Illinois, Urbana-Champaign
Stan Sclaroff, Boston University
Kaleem Siddiqi, Yale University
Alan Yuille, Smith-Kettlewell Eye Research Institute
Andrew Zisserman, Oxford University

REGISTRATION INFORMATION

IEEE Members \$40, Nonmembers \$50, Full-time Students \$20
On-line registration available through the CVPR registration web site:
<http://marathon.csee.usf.edu/cvpr97.html>
or the workshop website:
<http://marathon.csee.usf.edu/recognition.html>

> From: Dori Dov <dori@ie.technion.ac.il>
> Subject: Announcement: TC-2 Newsletter

Dear Colleagues:

It is my pleasure as TC-2 Chairperson to start the electronic Newsletter of the Technical Committee (TC-2) on Syntactic and Structural Pattern Recognition (SSPR) of the International Association for Pattern Recognition (IAPR).

If you wish to be added to the list (or removed) please email to bravo@ie.technion.ac.il and cc to me: dori@ie.technion.ac.il

In this message I will be brief and restrict myself to introduction. We have established a website in URL <http://iew3.technion.ac.il:8080/~sspr94/> and I would like to invite you to visit it. In particular it has a pointer to SSPR'98 to be held in Sydney, Australia in conjunction with ICPR in Brisbane, Aug. 1998. Another interesting pointer is to a comprehensive account on past SSPR workshops which was written with a lot of care and attention by Professor Alberto Sanfeliu, and I take this opportunity to thank him once again for this excellent work.

Please forward this message to colleagues and any professional who might be interested in being listed in the TC-2 Mailing list.
Best regards,
Dov.

Dr. Dov Dori
Information Systems Engineering
Faculty of Industrial Engineering and Management
Technion, Israel Institute of Technology
Haifa 32000, Israel
dori@ie.technion.ac.il tel. (972) 4 8294409; fax (972) 4 8235194
<http://iew3.technion.ac.il:8080/Home/Users/dori.phtml>

That's all for now.

Your TC10 chairman,

--
Atul K. Chhabra Phone: (914)644-2786
NYNEX Science & Technology Fax: (914)644-2561
500 Westchester Avenue Email: atul@nynexst.com
White Plains, NY 10604, USA

TC10 WWW URL: <http://www.iapr-tc10.or.kr/>
TC10 News submissions and subscription requests to: atul@nynexst.com